

Lecture 17: Tanner Codes

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1 Tanner Codes

Quantum Tanner codes are based off of classical Tanner codes. A Tanner code is a classical code based off a graph G . A Tanner code can be defined on a generic graph or on a bipartite graph. We will use the bipartite graph approach. Let $G = (V, E)$, where $V = L \sqcup R$ and all edges in G are between L and R , i.e. $(u, v) \in E$ implies $u \in L, v \in R$ or vice-versa. We shall also assume that $|L| = n|R|$ and that G is r -regular.

The number of edges in G is $|E| = n \cdot r = |L| \cdot r = m$. We define $E(u)$ to be the set of edges incident to u . To each edge we shall associate a bit. Codewords are defined by the bit string attained from the bits associated to each edge. So, the codewords have length m .

Definition 1.1. Let $G = (L, R, E)$ be an r -regular bipartite graph. Let $C_0 \subset \{0, 1\}^r$ be a ‘base’ code. Then, a Tanner code is

$$TC(G, C_0) = \{c \in \{0, 1\}^{|E|} : \forall v \in L \cup R, c|_{E(v)} \in C_0\}.$$

That is, the Tanner code is the set of $|E|$ -bit strings such that for each vertex, the bits associated to the edges incident to that vertex are in the base code C_0 . It is implied that for each vertex there is a known ordering of the edges that decides the order of the bits.

Fact 1.2. *If C_0 is linear, then $TC(G, C_0)$ is linear.*

Proof. Let $c, c' \in TC(G, C_0)$. Note that for any v , we have $(c + c')|_{E(v)} = c|_{E(v)} + c'|_{E(v)} \in C_0$. \square

Another way to see that the Tanner code is linear is by writing down its parity checks. Since C_0 is linear, there are $r - \dim(C_0)$ linearly independent parity checks. So, to check if a given string is a code word in the Tanner code, we just need to check that the edges on each vertex satisfy the parity checks. Since there are $2n$ vertices, there are at most $2n(r - \dim(C_0))$ linearly independent parity checks (we say at most, since it may turn out that some parity checks are implied by others).

Fact 1.3. *We have*

$$\dim(TC(G, C_0)) = \#bits - \#\text{linearly independent parity checks} \geq m - 2n(r - \dim(C_0)).$$

Write $\dim(C_0) = r \cdot R_0$ for $0 \leq R_0 \leq 1$. The bigger R_0 is, the better a code C_0 is since this means it encodes more bits. Then,

$$m - 2n(r - \dim(C_0)) = nr - 2n(r - \dim(C_0)) = nr(1 - 2(1 - R_0)) = nr(2R_0 - 1) = m(2R_0 - 1).$$

So, if we want $\dim(TC(G, C_0)) \in \Omega(m)$, then we need $R_0 \in (\frac{1}{2}, 1]$.

We want the code to not only have good dimension but also good distance. Getting good dimension is fairly easy, as we just showed; getting good distance is harder. We have to be careful about what graphs we use. Suppose C_0 has good distance $\Delta_0 \cdot r$ and let $c \in TC(G, C_0)$ be nonzero. We want to argue that c has high (Hamming) weight, since this implies that the Tanner code has good distance.

Since c is nonzero, at least one edge e in the graph is assigned a 1. Let $e = (u, v) \in L \times R$ and note that since $c|_{E(u)} \in C_0$, we have $|c|_{E(u)} \geq \Delta_0 \cdot r$. So, knowing that at least one edge incident to $u \in L$ is assigned a 1 implies that many edges are assigned 1. Each outgoing edge with a 1 on it meets a vertex $v_i \in R$, $i = 1, \dots, \Delta_0 \cdot r$. Applying the same argument to the vertices v_i shows that c must have very high weight, however this only holds if most of the edges with a 1 incident to each v_i all meet different vertices in L . That is, it may be the case that the graph has two sets of vertices $S \subset L$ and $T \subset R$ that only share edges with each other.

So, the idea is to look for graphs such that for small sets $S \subset L, T \subset R$, most edges from S go outside of T , i.e. $E(S, T) = \{\text{edges between } S \text{ and } T\}$ is small. This will prevent the bad situation from before where all edges with weight 1 are shared between two small sets. A good place to start is to look at random graphs.

Let G be a random r -regular bipartite graph. We calculate

$$\mathbf{E}[|E(S, T)|] = |S| \cdot r \cdot \frac{|T|}{n},$$

this follows since $|S| \cdot r$ is the number of edges coming out of S , and $|T|/n$ is the average fraction of those edges that go into T .

Definition 1.4. We say that a graph $G = (L, R, E)$ is ε -pseudorandom if $\forall S \subset L, \forall T \subset R$, we have

$$\left| |E(S, T)| - |S| \cdot r \cdot \frac{|T|}{n} \right| \leq \varepsilon r \sqrt{|S| \cdot |T|}.$$

Observe that we allow the ‘error’ to be larger if r , $|S|$, or $|T|$ is large.

Assuming that G is ε -pseudorandom, we show that the Tanner code $TC(G, C_0)$ has good distance. Set $S = \{u \in L : c|_{E(u)} \neq 0\}$ and $T = \{v \in R : c|_{E(v)} \neq 0\}$. Observe that $|c| \geq \max\{|S| \cdot \Delta_0 \cdot r, |T| \cdot \Delta_0 \cdot r\}$, so in particular, $|c| \geq \sqrt{|S| \cdot |T|} \Delta_0 \cdot r$. We show that most edges with a 1 go between S and T and hence $\sqrt{|S| \cdot |T|} \Delta_0 \cdot r \leq |c| \leq |E(S, T)|$.

By the ε -pseudorandomness, we have

$$\begin{aligned} \Delta_0 r \sqrt{|S| \cdot |T|} &\leq |c| \leq |E(S, T)| \leq \frac{r}{n} |S| \cdot |T| + \varepsilon r \sqrt{|S| \cdot |T|} \\ \Rightarrow (\Delta_0 - \varepsilon) r \sqrt{|S| \cdot |T|} &\leq \frac{r}{n} |S| \cdot |T| \\ \Rightarrow (\Delta_0 - \varepsilon) n &\leq \sqrt{|S| \cdot |T|}. \end{aligned}$$

So, either $|S|$ or $|T|$ is very large. Also, observe that this implies

$$|c| \geq \Delta_0 r \sqrt{|S| \cdot |T|} \geq \Delta_0 r (\Delta_0 - \varepsilon) n = \Delta_0 (\Delta_0 - \varepsilon) m.$$

So, if the base code has constant distance Δ_0 and the underlying graph is ε -pseudorandom with $\varepsilon < \Delta_0$, then the distance of the Tanner code = $\text{const} \cdot m$.

2 Expander Graphs

Intuitively, an expander graph is a graph in which any small set of vertices has a large neighborhood.

Fact 2.1. Let $G = (V, E)$ be a graph. Its adjacency matrix is given by

$$A(G) = \begin{cases} 1 & \text{if } (u, v) \in E \\ 0 & \text{otherwise,} \end{cases}$$

where the rows and columns are indexed by the vertices in V . We observe that $A(G)$ is an $n \times n$ real, symmetric matrix and therefore has eigenvalues $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_n$.

Fact 2.2. If G is r -regular, the vector $v = [1 \ 1 \ \dots \ 1]^T$ is an eigenvector with eigenvalue $\lambda_1 = r$.

Proof. Since G is r -regular, each row has exactly r entries equal to 1 and the rest are 0. So, $A(G)v = rv$. \square

Definition 2.3. A graph G is a λ -spectral expander if $\lambda = \max\{\lambda_2, |\lambda_n|\}$ is small.

Example 2.4. Consider a graph G with k connected components V_1, \dots, V_k . Then, there are k eigenvectors of the form $v_j = [a_1 \ \dots \ a_n]^T$ where $a_i = 1$ if and only if $i \in V_j$, i.e. the vector which is 1 only on the vertices in V_j . The associated eigenvalues are $|V_j|$. So, if there are at least two large connected components, the largest two eigenvalues are not small and so G is not an expander.

Definition 2.5. The double cover of a graph $G = (V, E)$ is a bipartite graph $G' = (V_L, V_R, E')$ where $|V_L| = |V| = |V_R|$. To each edge $v \in V$, we associate a vertex $v_L \in V_L$ and a vertex $v_R \in V_R$. We have that $(u_L, v_R) \in E' \subset V_L \times V_R$ if and only if $(u, v) \in E$. The bipartite adjacency matrix of the double cover has its rows indexed by vertices in V_L and the columns indexed by the vertices in V_R , with a 1 entry if and only if $(v_L, v_R) \in E'$. In particular the bipartite adjacency matrix of G' is just the adjacency matrix $A(G)$ of G .

Fact 2.6. *If $G = (V, E)$ is a λ -spectral expander, then its double cover is $(\frac{\lambda}{r})$ -pseudorandom.*

Proof. Let $A(G)$ be the adjacency matrix of G and expand it in an eigenbasis.

$$A(G) = \sum_{i=1}^n \lambda_i |v_i\rangle \langle v_i|,$$

where we know that $\lambda_1 = r$ and we normalize $|v_1\rangle = \frac{1}{\sqrt{n}}[1 \dots 1]^T = \frac{1}{\sqrt{n}}(|1\rangle + \dots + |n\rangle)$. Let $S, T \subset V$ and define

$$|S\rangle = \sum_{i \in S} |i\rangle.$$

Then,

$$\begin{aligned} |E(S, T)| &= \langle S | A(G) | T \rangle = \sum_{i=1}^n \lambda_i \langle S | v_i \rangle \langle v_i | T \rangle \\ &= \lambda_1 \langle S | v_1 \rangle \langle v_1 | T \rangle + \sum_{i \geq 2} \lambda_i \langle S | v_i \rangle \langle v_i | T \rangle \\ &= \frac{r}{n} |S| \cdot |T| + \sum_{i \geq 2} \lambda_i \langle S | v_i \rangle \langle v_i | T \rangle \end{aligned}$$

Therefore,

$$\begin{aligned} \left| |E(S, T)| - \frac{r}{n} |S| \cdot |T| \right| &= \left| \sum_{i \geq 2} \lambda_i \langle S | v_i \rangle \langle v_i | T \rangle \right| \\ &\leq \sum_{i \geq 2} |\lambda_i| \cdot |\langle S | v_i \rangle| \cdot |\langle v_i | T \rangle| \\ &\leq \lambda \sum_{i \geq 1} |\langle S | v_i \rangle| \cdot |\langle v_i | T \rangle| \\ &\leq \lambda \sqrt{\sum_{i \geq 1} |\langle S | v_i \rangle|^2} \sqrt{\sum_{i \geq 1} |\langle v_i | T \rangle|^2} \\ &= \lambda \sqrt{\sum_{i \geq 1} \langle S | v_i \rangle \langle v_i | S \rangle} \sqrt{\sum_{i \geq 1} \langle T | v_i \rangle \langle v_i | T \rangle} \\ &= \lambda \sqrt{\langle S | S \rangle} \sqrt{\langle T | T \rangle} \\ &= \lambda \sqrt{|S| \cdot |T|} \\ &= \frac{\lambda}{r} r \sqrt{|S| \cdot |T|}. \end{aligned}$$

□

Example 2.7. *Another example of a graph which is not an expander graph is any r -regular bipartite graph. By regularity, $|L| = |R|$, so the vector $v = [1 \ 1 \ \dots \ -1 \ -1]^T$ (the 1's are in positions indexed by vertices in L and the -1 's are in positions indexed by vertices in R) is an eigenvector with eigenvalue $-r$.*

We care about expander graphs since there are known efficient algorithms for generating expander graphs. Recall the distance of the Tanner code is given by $\Delta_0(\Delta_0 - \varepsilon)m$, while the dimension is $m(2R_0 - 1)$. So, if the inner code has good distance Δ_0 and rate R_0 , our work above shows that we can efficiently generate a good Tanner code.